

## Homework #5: Chapter 2 (due Oct. 2, 2015)

### Preliminary

- Textbook reading Ch. 2.4 - 3.2 (pp. 116 - 186)
- As a reminder, EE312 office hours are on Wed. from 9:00-10:00am and Thu. from 3:00-4:00pm.
- Please direct all email to [pdeleon@nmsu.edu](mailto:pdeleon@nmsu.edu) (do not send email via Canvas). All requests for bonus points will receive a confirmation email within 48 hours.
- In order to receive full credit for homework problems, you must provide a detailed solution. Simply writing a few, summarized steps toward the answer will result in minimal credit.
- All problems are worth +10 points unless otherwise noted.

### Textbook Problems

2.31

2.33(a) only (ii)

2.38(a)

2.39(a)

### Software Problems

Using `impz(b,a)` in MATLAB, we can numerically compute and plot the impulse response. For more information, please see

<http://www.mathworks.com/help/signal/ref/impz.html>

1. Reconsider the system in Homework #4 Problem 2.30:  $y[n] + 2y[n-1] = x[n]$ . As described in (2.113) in the text, we can place the LCCDE coefficients for feedback and feedforward into vectors  $\mathbf{a} = [1; 2]$  and  $\mathbf{b} = [1]$ . Use the following MATLAB code to plot the impulse response and print (in a list) the values,  $h[n]$  for  $0 \leq n \leq 10$ .

```
N = 10;
a = [1;2]; % feedback coeffs
b = [1]; % feedforward coeffs
h = impz(b,a,N+1);
[[0:N]' h] % list the values
plotdsig(h); % use tool for quick DT plot
axis([0 10 -1024 1024]);
ylabel('h[n]');
```