


```
>> plot(w,abs(H));
>> ylabel('|H(e^{j\omega})|');xlabel('\omega (radians/sample)');
>> figure(2)
>> plot(w,angle(H)); % plot phase response in figure 2 window
```

3. Consider the ideal delay system in Example 5.11. From previous work the LCCDE is given by

$$y[n] = x[n - n_0]$$

and the impulse response and frequency response are

$$h[n] = \delta[n - n_0] \leftrightarrow H(e^{j\omega}) = e^{-j\omega n_0}.$$

Let $n_0 = 10$ and plot the magnitude and phase response from $0 \leq \omega \leq \pi$. Since the system is a simple delay there is no magnitude impact on frequencies (hence a flat magnitude response) but the phase response is $-\omega n_0$. From your plot, verify the phase response slope is $-n_0$.

Frequency Spectrum of a DT Signal

The frequency spectrum of a DT signal, $x[n]$ may be computed using the MATLAB command

```
>> X = fft(x,N);
```

which returns $X(e^{j\omega})$ at N evenly spaced frequencies between 0 and 2π ,

$$\mathbf{X} = [X(e^{j\omega_0}), X(e^{j\omega_1}), \dots, X(e^{j\omega_{N-1}})]^T$$

where $\omega_k = 2\pi k/N$. We visualize the frequency spectrum by plotting the magnitude spectrum and phase spectrum of the signal using the MATLAB commands

```
>> w = [0:2*pi/N:2*pi-2*pi/N]'; % frequency vector from 0 to 2\pi in steps of 2\pi/N
>> figure(1)
>> plot(w,abs(X)); % plot magnitude spectrum in figure 1 window
>> ylabel('|X(e^{j\omega})|');xlabel('\omega (rads/sample)');
>> figure(2)
>> plot(w,angle(X)); % plot phase spectrum in figure 2 window
>> ylabel('\angle X(e^{j\omega})');xlabel('\omega (radians/sample)');
```