



New Mexico State University
Klipsch School of Electrical Engineering

EE555 - Advanced Linear Systems
Spring 2005
Exam #1

Name: _____

Prob. 1	/	5 points
Prob. 2	/	5 points
Prob. 3	/	10 points
Prob. 4	/	15 points
Prob. 5	/	25 points
Prob. 6	/	25 points
Prob. 7	/	15 points
Total	/	100 points

Prob. 1

Show that if \mathbf{A} and \mathbf{B} are $n \times n$ matrices, then \mathbf{AB} and \mathbf{BA} have the same characteristic polynomial or equivalently have the same eigenvalues even if $\mathbf{AB} \neq \mathbf{BA}$.

Prob. 2

Find the minimum polynomial, $\mu(s)$ of the matrix

$$\mathbf{A} = \begin{bmatrix} 2 & 1 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 5 \end{bmatrix}.$$

Prob. 3

(Mullis p. 54 Exercise) With

$$\mathbf{N}_i = \mathbf{E}_i (\mathbf{A} - \lambda_i \mathbf{I})$$

show that

(i) $\mathbf{N}_i^k = \mathbf{E}_i (\mathbf{A} - \lambda_i \mathbf{I})^k$

(ii) $\mathbf{N}_i^{n_i} = \mathbf{0}$ where n_i is the multiplicity of λ_i

(iii) For $i \neq j$, $\mathbf{N}_i \mathbf{E}_j = \mathbf{E}_j \mathbf{N}_i = \mathbf{N}_i \mathbf{N}_j = \mathbf{0}$

Prob. 4

Let

$$\mathbf{b} = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

and consider the system of linear equations

$$\mathbf{Ax} = \mathbf{b}$$

For each of the following matrices, determine the subspaces $\text{Range}(\mathbf{A})$ and $\text{Null}(\mathbf{A})$. Based on these subspaces also determine whether or not there is a solution for \mathbf{x} and if so, whether it is unique or not. You do not have to actually compute \mathbf{x} although you may choose to do so if it helps.

(i) $\mathbf{A} = \begin{bmatrix} 1 & 0 \\ 2 & 3 \end{bmatrix}$

(ii) $\mathbf{A} = \begin{bmatrix} 0 & 3 \\ 1 & 2 \end{bmatrix}$

(iii) $\mathbf{A} = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}$

(iv) $\mathbf{A} = \begin{bmatrix} 1 & -2 \\ -2 & 4 \end{bmatrix}$

(v) $\mathbf{A} = \begin{bmatrix} -1 & 2 \\ 3 & -6 \end{bmatrix}$

Prob. 5

Consider the discretized Newtonian equations for motion

$$\begin{aligned}d(n+1) &= d(n) + v(n)T + \frac{1}{2}a(n)T^2 \\v(n+1) &= v(n) + a(n)T\end{aligned}$$

where $d(n)$, $v(n)$, and $a(n)$ are the distance, velocity, and acceleration (respectively) at time index n and T is the sample period. Define a state vector,

$$\mathbf{x}(n) = \begin{bmatrix} d(n) \\ v(n) \\ a(n) \end{bmatrix}.$$

(i) Let

$$\mathbf{x}(n+1) = \mathbf{A}\mathbf{x}(n)$$

be a *state update equation*. Determine the *state transition matrix*, \mathbf{A} assuming constant acceleration, i.e. $a(n+1) = a(n)$.

(ii) Show that

$$\mathbf{x}(n+k) = \mathbf{A}^k \mathbf{x}(n).$$

(iii) For \mathbf{A} found in (i), determine the eigenvalues, λ_i and multiplicities, n_i ; the projections, \mathbf{E}_i ; and (if applicable) the nilpotent matrices, \mathbf{N}_i . Do not make any assumptions on T .

(iv) Assuming an initial distance of 0 m, initial velocity of 0 m/s, constant acceleration of 1 m/s², and a sample period of 1 s, determine the distance and velocity at $n = 100$. You *must* use your results in (iii) and the function calculus [either or p.42 (12) or p. 54 (18)] to compute your answer—direct calculation using the Newtonian equations (with $T = 100$) or brute force matrix multiplications will not be accepted.

Prob. 6

Repeat Prob. 5, except that now the acceleration doubles every sample period, i.e.

$$a(n+1) = 2a(n)$$

(i) Determine the state transition matrix, \mathbf{A} .

(ii) For \mathbf{A} found in (i), determine the eigenvalues, λ_i and multiplicities, n_i ; the projections, \mathbf{E}_i ; and (if applicable) the nilpotent matrices, \mathbf{N}_i . Do not make any assumptions on T .

(iii) Assuming an initial distance of 0 m, initial velocity of 0 m/s, initial acceleration of 1 m/s^2 , and a sample period of 1 s, determine the distance, velocity, and acceleration at $n = 10$. You *must* use your results in (ii) and the function calculus [either eq. (12) on p. 42 or eq. (18) on p. 54] to compute your answer—brute force matrix multiplications will not be accepted.

Prob. 7

(Mullis p. 41 Exercise) Let

$$\psi(s) = \begin{bmatrix} 1 \\ s \\ \vdots \\ s^{n-1} \end{bmatrix}$$

and

$$\begin{aligned} \mathbf{V} &= \begin{bmatrix} \psi(\lambda_1) & \dots & \psi(\lambda_n) \end{bmatrix} \\ &= \text{Vandermonde}(\lambda_1, \dots, \lambda_n) \end{aligned}$$

(assume distinct $\{\lambda_1, \dots, \lambda_n\}$). Show that

(i)

$$\begin{bmatrix} e_1(s) \\ \vdots \\ e_n(s) \end{bmatrix} = \mathbf{V}^{-1}\psi(s)$$

Hint: Solve $\mathbf{V}\mathbf{x} = \psi(s)$ and show $x_k = e_k(s)$.

(ii)

$$\sum_{k=1}^n \lambda_k^m e_k(s) = s^m, \text{ for } 0 \leq m \leq n-1$$